

# Spiking Reasoning System

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## Abstract

© 2017 IEEE. In this position paper the new approach for the spiking reasoning system for the real-time processing of a robotic system is presented. This is the development of the 'Robot dream' architecture presented earlier, specifically the real-time robotic management system. The main idea of the architecture is inherited from our previous works on machine cognition that have their roots in works of Marvin Minsky, specifically 'model of six' as six levels of the mental activity. The principal approach for the high-level architecture and provide examples of the data structures of the spiking reasoning system and robotic system management architecture was demonstrated.

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## Keywords

ai, cognition, human, robot

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