

RINGS OF \mathfrak{h} -DEFORMED DIFFERENTIAL OPERATORS

O. V. Ogievetsky*[†] and B. Herlemont*

We describe the center of the ring $\text{Diff}_{\mathfrak{h}}(n)$ of \mathfrak{h} -deformed differential operators of type A. We establish an isomorphism between certain localizations of $\text{Diff}_{\mathfrak{h}}(n)$ and the Weyl algebra W_n , extended by n indeterminates.

Keywords: reduction algebra, oscillatory realization, ring of differential operators, Gelfand–Kirillov conjecture, dynamical Yang–Baxter equation

DOI: 10.1134/S0040577917080104

In memory of Petr Kulish

1. Introduction

The ring $\text{Diff}_{\mathfrak{h}}(n)$ of \mathfrak{h} -deformed differential operators of type A appears in the theory of reduction algebras. A reduction algebra $R_{\mathfrak{g}}^A$ provides a tool for studying decompositions of representations of an associative algebra \mathcal{A} with respect to its subalgebra in the situation where this subalgebra is the universal enveloping algebra of a reductive Lie algebra \mathfrak{g} [1], [2] (see [3], [4] for the definition, general theory, and uses of reduction algebras).

Decompositions of tensor products of representations of a reductive Lie algebra \mathfrak{g} is a particular case of a restriction problem associated with the diagonal embedding of $U(\mathfrak{g})$ into $U(\mathfrak{g}) \otimes U(\mathfrak{g})$. The corresponding reduction algebra, denoted by $\mathcal{D}(\mathfrak{g})$, is called a *diagonal reduction algebra* [5]. A description of the diagonal reduction algebra $\mathcal{D}(\mathfrak{gl}_n)$ in terms of generators and (ordering) defining relations was given in [5], [6].

The diagonal reduction algebra $\mathcal{D}(\mathfrak{gl}_n)$ admits an analogue of the *oscillator realization* in the rings $\text{Diff}_{\mathfrak{h}}(n, N)$, $N = 1, 2, 3, \dots$, of \mathfrak{h} -deformed differential operators (see [7]). The ring $\text{Diff}_{\mathfrak{h}}(n, N)$ can be obtained by the reduction of the ring of differential operators in nN variables (i.e., of the Weyl algebra $W_{nN} = W_n^{\otimes N}$) with respect to the natural action of \mathfrak{gl}_n . Similarly to the ring of q -differential operators [8], the algebra $\text{Diff}_{\mathfrak{h}}(n, N)$ can be described in the R-matrix formalism. The R-matrix needed here is a solution of the so-called dynamical Yang–Baxter equation (see [9]–[11] for different aspects of the dynamical Yang–Baxter equation and its solutions).

*Aix Marseille Univ, Université de Toulon, CNRS, CPT, Marseille, France, e-mail: oleg@cpt.univ-mrs.fr, herlemont.basile@hotmail.fr.

[†]Kazan Federal University, Kazan, Russia; On leave of absence from Lebedev Physical Institute, RAS, Moscow, Russia.

The research of O. V. Ogievetsky was supported by the Program of Competitive Growth of Kazan Federal University and the Russian Foundation for Basic Research (Grant No. 17-01-00585).

Prepared from an English manuscript submitted by the authors; for the Russian version, see *Teoreticheskaya i Matematicheskaya Fizika*, Vol. 192, No. 2, pp. 322–334, August, 2017.